

# Pegasus-35H™

By Castle Creations™

Micro Digital Helicopter Motor Control

**Warning!** High power motor systems can be very dangerous! High currents can heat wires and batteries, causing fires and burning skin. Follow the wiring directions carefully! Model helicopters equipped with high power motors can kill. Always fly at a sanctioned field. Never fly over or near spectators. Even though this controller is equipped with a safety arming program, you should still use caution when connecting the

## 1.0 Features of the Pegasus-35H™:

- Microprocessor controlled
- Low Resistance (.0011 ohms)
- High rate (2800 Hz) switching (PWM)
- Up to 35 Amps continuous current (with proper air flow)
- Battery Eliminator Circuit (BEC) provides power to receiver and servos - eliminates separate receiver battery
- Audible arming signal alerts when system is armed
- Six to eight cells with three standard micro servos and gyro
- Six to eight cells with two high-torque micro servos and gyro
- Up to ten cells with two standard micro servos and gyro
- Eighteen cells MAX with BEC disabled.
- Safe “power on” arming program ensures motor will not accidentally turn on
- Low torque “soft start” prevents damage to fragile gearboxes
- Auto shut down when signal is lost or radio interference becomes severe
- Rugged surface mount construction

## 2.0 Wiring Your Pegasus-35H™:

### Tools required:

Wire cutters      Wire strippers (optional)  
Soldering Iron (25-40 watts - Do not use a soldering “gun”)

### Parts required:

Solder (rosin core “electronic” solder - do not use acid core “plumbers” solder)  
Battery connector

## 2.1 Adding the Battery Connector

The battery connector is attached to the left side of the controller (looking down at the heat sink/label). Cut the wires to the length you require on the battery side. Strip off of the wire insulation to expose just enough wire to attach the battery connector. (Note: if you do not have a pair of wire strippers, you can use a modeling knife to carefully cut through the insulation around the wire. Then the insulation should easily pull off the wire.) Attach the battery connector to the wires ENSURING THAT THE POLARITY

(red wire to battery red wire, black wire to battery black wire) IS CORRECT, following the instructions for the battery connector.

## 2.2 Attaching the Motor Leads

The motor is connected to the right side of the controller (looking down at the heat sink/label). Cut the wires to the length you require on the motor side. Strip the wire insulation to expose just enough wire to solder the wires to the motor terminals. (Note: If you do not have a pair of wire strippers, you can use a modeling knife to carefully cut through the insulation around the wire. Then the insulation should easily pull off the wire). There should be a ‘+’ symbol or a RED DOT on the end of your motor which indicates which terminal must be connected to the RED wire. Connect the other terminal to the white wire. A fuse (30-45 amps) may be connected inline in either the black or red power wire. A fuse is recommended for the safest operation. **DO NOT PLACE A FUSE IN THE CIRCUIT BETWEEN THE BATTERY AND SPEED CONTROL. YOU COULD LOSE CONTROL OF THE MODEL.**

Align the wires carefully and solder to the motor terminals. Ensure that all connections (battery and motor) are correctly polarized.

**IMPORTANT NOTE:** YOU MUST BE SURE THAT ALL CONNECTIONS ARE CORRECT WHEN CONNECTING THE SPEED CONTROL. Incorrectly connecting the speed control could cause permanent damage to the controller.

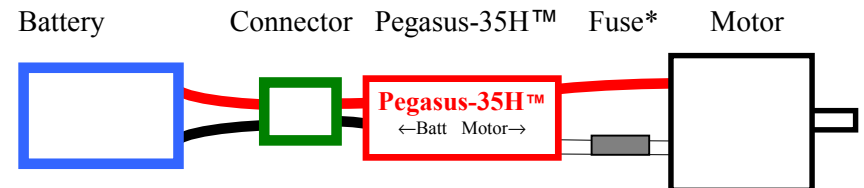


Fig 1: System power wiring diagram

\* Suggested 30-45 Amp

## 2.3 Connecting the Receiver

Connect the receiver lead (the three color, twisted wires with a connector on the end) to the throttle channel on your receiver (usually channel 3). Do not connect a battery to the receiver, as the Pegasus-35H™ will supply power to the receiver and servos through the receiver connector. If you are using more than ten cells, you will need to use a separate receiver battery. See the section 4.0 (under the heading BEC) for instructions on disabling the BEC to use a separate receiver battery.

**ALWAYS PERFORM A RANGE CHECK BEFORE FLYING WITH ANY NEW SPEED CONTROL! PERFORM YOUR RANGE CHECK AT FULL THROTTLE, HALF THROTTLE AND NO THROTTLE.**

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## 3.0 Flying with Your Pegasus-35H™:

*Initialization sequence:*

1. Connect the speed controller receiver connector to the proper channel on your receiver (usually channel 3)
2. Turn on your transmitter.
3. Connect the main power battery to the speed controller. A single “beep” will be emitted.
4. The speed controller will remain unarmed (will not operate) until it sees more than four seconds of “OFF” throttle. Move the throttle arm to the lowest position on your transmitter, wait at least four seconds. Two “beeps” will sound alerting that system is armed. Test the controller to make sure that the throttle operates.
5. Go fly!

## 4.0 Using the Features of Your Pegasus-35H™

**BEC** - The BEC power is supplied to the receiver and servos through the receiver connector wires. If you wish to disable the BEC and use a separate receiver battery (required for the use of more than ten cells), you must first cut the red wire in the trio of receiver wires. Simply use a pair of wire cutters to remove a short section of the red wire near the receiver connector, and be sure to insulate the cut wire with a bit of electrical tape. Then you may safely use a battery with your receiver.

**Loss of Transmitter Signal**, or excessive radio noise cutoff - Motor cutoff will also occur if the signal from the transmitter is lost, or if the radio noise becomes excessive. After radio connection has been reestablished, the motor can be restarted by moving the throttle to the braking position (full off) for four seconds.

**Safe Power Up** - The Safe Power up feature is a “finger saver”, designed to prevent the motor from starting accidentally on power up. To arm the controller, the transmitter stick must be held in the “OFF” position (all the way down) for at least four seconds. Until the controller is armed, it will not provide any power to the motor, regardless of where the throttle stick on your transmitter is positioned. Before flying your model, be sure to “blip” the throttle to ensure that the controller is armed.

## 5.0 Troubleshooting

**Everything is hooked up correctly, the BEC (receiver and servos) works, but the throttle does not work.**

The controller is not seeing the four seconds of “dead space” (low throttle) and is not arming. Try moving your throttle stick all the way down, and moving the trim all the way down. Wait for four seconds and try the throttle again. If it still does not arm, you may need to reverse the throttle control on your transmitter (see your radio documentation). You may also check to make sure that your endpoint adjustments on your radio (if it has them) are set all the way open.

**Nothing seems to work, receiver and servos are dead, and the throttle is dead.**

Check all connections to ensure that they are correct, and that the polarity (+/-) connections are correct. Ensure that the battery is not connected to the motor side of the speed controller. If everything is

correctly connected, and the receiver and servos still do not work, contact the dealer where you purchased your Pegasus-35H™ or contact **Castle Creations™** directly. (see info below)

## 6.0 CONTACT/WARRANTY INFORMATION

Your Pegasus-35H™ is warranted for 1 year from date of purchase to be free from manufacturing and component defects. This warranty does not cover abuse, neglect, or damage due to incorrect wiring, over voltage, or overloading. If you have any questions, comments, or wish to return your Pegasus-35H™ for warranty or after warranty repair/replacement contact **Castle Creations™** at:

### Castle Creations

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